# nuXmv: infinite state model checking

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# Infinite state transition system

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- decidability,
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What about computational models?

- Turing machine,
- 3-counter machine,
- 2-counter machine.

### Finite models

- Up until now we have seen only finite models: representable as finite graphs.
- Nice theoretical results: *decidability* for both reachability and liveness.
- Sound and complete procedures: if a counter-example exists, then there exist also a looping counter-example.

# Sources of infinity

- data manipulation:  $\mathbb{N}$ ,  $\mathbb{Z}$ ,  $\mathbb{Q}$ ,  $\mathbb{R}$ ;
- control structures: procedures, process creation;
- async communication: unbounded FIFOs;
- parameterised models: check correctness for all possible parameters;
- time: timed/hybrid systems;
- . . . .

## Infinite state

- Represent an infinite graph (infinite number of states).
- There might be no looping counter-example, does **not** imply that the property holds. **Why**?

### Where are the problems?

- $M \models \psi$
- $\mathcal{L}(M) \subseteq \mathcal{L}(T_{\psi})$
- $\mathcal{L}(M) \cap \mathcal{L}(T_{\neg \psi}) = \emptyset$
- $\mathcal{L}(M \times T_{\neg \psi}) = \emptyset$

# **nuXmv** supports the description of infinite state transition systems through the types: integer ( $\mathbb{Z}$ ) and real ( $\mathbb{R}$ ).



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Invariant, LTL and CTL checking are undecidable.

# **Timed Automata**

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- Bisimulation with a finite state transition system: *region-abstraction*.

## **BMC** and K-induction

- BMC and K-induction can be *trivially* extended to infinite-state systems.
- They are still sound, we loose completeness:
  - BMC : look for looping counter-example,
  - K-induction : bad state reachable by infinite run without initial states.
- Use an SMT-solver able to handle required theories: *integers*, *reals*.

Other techniques have been adapted for infinite-state systems: *liveness-to-safety, ic3, abstract-interpretation* ....

# **Exercises**

#### Check if the 2 counters contain the same value

- Write a program for a 2-counter machine that decides whether the counters contain the same value.
- Model this program in NUXMV.
- Prove termination and correctness.

### pseudocode

```
while(true):
    if c0 == 0:
        return c1 == 0
    if c1 == 0:
        return c0 == 0
    c0--;
    c1--;
```

# Straightforward translation into SMV

MODULE main VAR

- c0 : integer;
- c1 : integer;
- 1 : {check, decr\_c0, decr\_c1, end\_equal, end\_not\_equal};

INVAR  $c0 \ge 0 \& c1 \ge 0;$ 

```
ASSIGN
  init(l) := check;
  next(1) :=
    case
      l = check \& c0 = 0 \& c1 = 0 : end_equal;
      l = check \& c0 = 0 \& c1 != 0 : end_not_equal;
      l = check \& c0 != 0 \& c1 = 0 : end_not_equal;
      l = check : decr_c0;
      l = decr_c0 : decr_c1;
      l = decr_c1 : check;
      l = end_equal : end_equal;
      l = end_not_equal : end_not_equal;
    esac;
```

```
ASSIGN next(c0) :=
  case
    1 = decr c0 \& c0 > 0 : c0 - 1;
    TRUE : c0;
  esac;
ASSIGN next(c1) :=
  case
    l = decr_c1 \& c1 > 0 : c1 - 1;
    TRUE : c1;
  esac;
```

## Properties

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LTLSPEC F (l in {end\_equal , end\_not\_equal}); What happens when we ask the system to verify this property? Do you have an intuition about why this is the case?

# Thermostat

# Model

- a thermostat has 2 states: on and off.
- at every clock tick the thermostat checks the current temperature:
  - if the temperature is below 18 degrees the thermostat switches *on*.
  - if the temperature is above 18 degrees the thermostat switches *off.*
- when the thermostat is *off* the temperature drops; the drop in temperature is at most *max\_dt* degrees.
- when the thermostat is *on* the temperature increases; the increase in temperature is at most *max\_dt* degrees.
- the temperature initially is in  $[18 max_dt; 18 + max_dt]$ .

Prove that the thermostat keeps the temperature in the range  $[18 - max_dt; 18 + max_dt]$ , for all  $max_dt$  in  $\mathbb{R}$ .

```
MODULE main
DEFINE threshold := 18:
FROZENVAR max dt : real;
VAR
  temperature : real;
  state : {on, off};
INIT temperature >= threshold - max_dt;
INIT temperature <= threshold + max dt;
INVAR temperature < threshold -> state = on:
INVAR temperature > threshold -> state = off;
TRANS state = off -> next(temperature) < temperature &
                      next(temperature) >= temperature - max dt;
TRANS state = on -> next(temperature) > temperature &
                      next(temperature) <= temperature + max dt;</pre>
INVARSPEC temperature >= threshold - max_dt &
          temperature <= threshold + max_dt;</pre>
```